

# Frame-Wise Breath Detection with Self-Training: An Exploration of Enhancing Breath Naturalness in Text-to-Speech

Dong Yang<sup>1,2</sup>, Tomoki Koriyama<sup>1</sup>, Yuki Saito<sup>2</sup>

<sup>1</sup>CyberAgent, Inc., Japan; <sup>2</sup>The University of Tokyo, Japan



CyberAgent AI Lab



↑ Code & speech samples

## Overview



Hmm I think that ... [Inhale] we should [click] go

(Filled Pause) (Silence) (Breath) (Tongue Click)

Breath synthesis remains underexplored in Text-to-Speech (TTS) research.

### 1. Breath Detection (Our Focus)

- Develop a rule-based approach for initial labeling
  - Avoid extensive manual annotation of training data
- Propose and train our breath detection model
  - Frame-wise detection with reduced computational costs
  - Self-training method on a large TTS corpus

### 2. Speech Synthesis (For Validation)

- Insert breath marks to text transcripts based on detection results
- Train a TTS model
  - Achieve more natural breath-contained synthetic speech

## Acoustic Features

### Duration<sup>[1]</sup>

### Zero-Crossing Rate (ZCR)<sup>[2]</sup>

Definition: Rate of the audio signal changes its sign

For discrete sampled signal:

$N$ : window length,  $X = \{x[n]\}_{n=0}^{N-1}$ : audio signal

$$ZCR(X) = \frac{1}{N-1} \sum_{n=1}^{N-1} 0.5 | \text{sgn}(x[n]) - \text{sgn}(x[n-1]) |$$

### Variance of Mel-Spectrogram (VMS)

Definition:  $\text{Var}(\text{Mel})$  in frequency domain

### Normalized Average of VMS (NA-VMS)

Definition: mean of min-max normalized VMS

$F$ : frame,  $V = \{v[f]\}_{f=0}^{F-1}$ : audio signal

$$NA-VMS(V) = \frac{1}{F} \sum_{f=0}^{F-1} \frac{v[f] - \min(V)}{\max(V) - \min(V)}$$

## Dataset & Annotation

LibriTTS-R<sup>[3]</sup> Corpus + MFA<sup>[4]</sup> for text-speech alignment & pause recognition

Manual annotation for valid & test sets:

	Utterances	Pauses	Annotated breath
Validation set	520	2,049	400
Test set	455	2,051	480

Rule-based annotation for training set:

Class	Duration	Max(VMS)	Max(ZCR)	NA-VMS	Precision	Recall
Breath	> 300 ms	> 150	> $1 \times 10^{-4}$	> 0.6	0.982	0.450
Non-breath	-	< 150	< $5 \times 10^{-5}$	-	1.000	0.111

## Self-Training Process

$\text{label}(T, P, B, U)$ :

All frames in training set:  $T$

- MFA-recognized pauses:  $P$
- Non-pauses:  $T \setminus P \rightarrow 0$
- Annotated breath:  $B \rightarrow 1$
- Annotated non-breath:  $U \rightarrow 0$
- Unannotated:  $P \setminus (B \cup U) \rightarrow -100$

Algorithm: **Self-training** for breath detection models

Initialize:

$k \leftarrow 0$

$Y^0 \leftarrow \text{label}(T, P, B, U)$

$D_\theta^0 \leftarrow \text{BCE}(D_\theta(T), Y^0)$

Repeat:

$k \leftarrow k + 1$

$\alpha^k \leftarrow \text{argmin}_{\alpha^k} | \text{Precision}(D_\theta^{k-1}(P_{\text{valid}}) > \alpha^k, B_{\text{valid}}) - (0.97 - 0.02 * k) |$

$\beta^k \leftarrow \text{argmin}_{\beta^k} | \text{Precision}(D_\theta^{k-1}(P_{\text{valid}}) < \beta^k, U_{\text{valid}}) - (0.97 - 0.02 * k) |$

$\hat{B} \leftarrow D_\theta^{k-1}(T) > \alpha^k$

$\hat{U} \leftarrow D_\theta^{k-1}(T) < \beta^k$

$Y^k \leftarrow \text{label}(T, P, B \cup \hat{B}, U \cup \hat{U}) \triangleright$  Pseudo-labeling

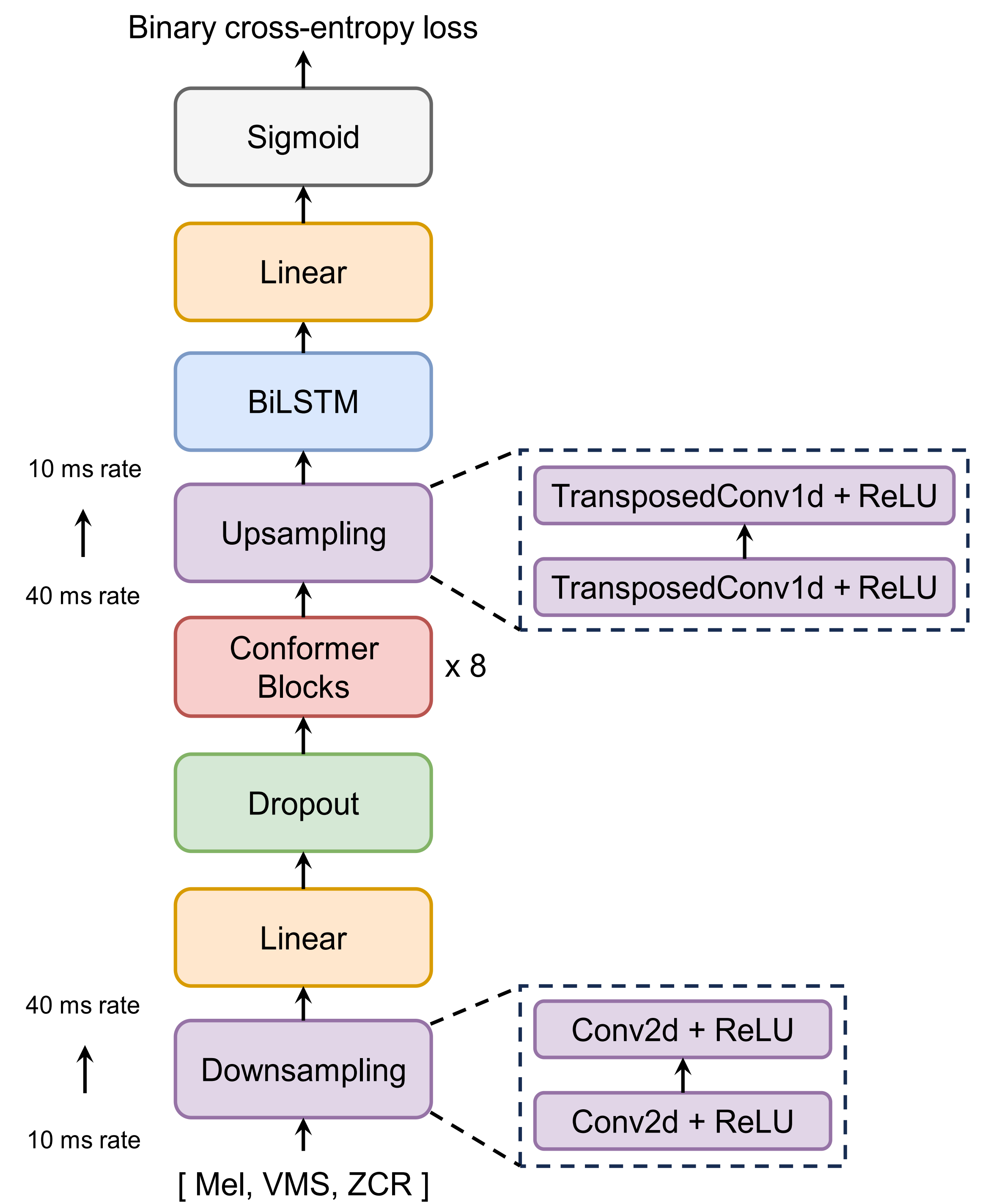
$D_\theta^k \leftarrow \text{BCE}(D_\theta^{k-1}(T), Y^k)$

$\gamma^k \leftarrow \text{argmax}_{\gamma^k} \text{IoU}(D_\theta^k(T_{\text{valid}}) > \gamma^k, B_{\text{valid}})$

Until:  $\text{IoU}(D_\theta^k(T_{\text{valid}}) > \gamma^k, B_{\text{valid}}) < \text{IoU}(D_\theta^{k-1}(T_{\text{valid}}) > \gamma^{k-1}, B_{\text{valid}})$

Output:  $D_\theta^{k-1}$

## Proposed Model



## Experimental Results

Breath detection experiments:

Metric: intersection over union (IoU)

Iteration	Baseline <sup>[5]</sup>	Proposed
0	0.616	0.777
1	0.634	0.809
2	0.681	0.829
3	<b>0.710</b>	<b>0.836</b>
4	0.709	0.827

Training configurations:

- Optimizer: AdamW
- Scheduler: Linear
- Peak learning rate:  $2 \times 10^{-5}$
- Epoch: 10
- Batch size: 64
- Dataset: train-clean-100, train-other-500

- Our proposed model consistently outperformed the baseline model.
- Both models achieved their peak IoU after the 3<sup>rd</sup> training iteration, where the models were considered the best-performing ones and used in the TTS experiments.

Ablation studies:

Model	Iteration	IoU
Proposed	0	0.777
w/o ZCR		0.631
w/o VMS		0.677
w/o non-breath		0.702
Proposed	1	0.809
w/o pseudo-label		0.740

- ZCR and VMS in the input and the use of non-breath set proved to be critical.
- Continued training without pseudo-labeling did not improve performance.

TTS experiments:

TTS model: VITS<sup>[6]</sup>; Dataset: train-clean-360

Model	MOS1 ± CI	MOS2 ± CI
Ground truth	4.03 ± 0.12	3.92 ± 0.13
VITS	3.35 ± 0.15	3.34 ± 0.17
VITS w/ baseline	3.27 ± 0.15	3.50 ± 0.14
VITS w/ proposed	<b>3.37 ± 0.14</b>	<b>3.55 ± 0.15</b>

MOS1:

- General evaluation
- Samples: Not all utterances included breath
- Conclusion: Inaccurate breath detection negatively affected the TTS training

MOS2:

- Breath-focus evaluation
- Samples: All utterances included breath
- Instruction: "Please focus on the breath sounds"
- Conclusion: Detected breath marks enhanced the naturalness of synthetic breath sounds

[1] N. Braunschweiler and L. Chen, SSW 2015.

[2] D. Ruinskiy and Y. Lavner, TASLP 2007.

[3] Y. Koizumi et al., INTERSPEECH 2023.

[4] M. McAuliffe et al., INTERSPEECH 2017.

[5] E. Székely et al., ICASSP 2019.

[6] J. Kim, J. Kong, and J. Son, ICML 2021.